

$\text{Si } \det T \neq 0 \Rightarrow \exists T^{-1} / TT^{-1} = I$
 $\hookrightarrow \lambda \neq 0;$

$$\begin{aligned}
 & \underline{\det(T^{-1} - \lambda^{-1}I)} = \\
 & \Rightarrow \det(T^{-1} - \lambda^{-1}TT^{-1}) = \\
 & \Rightarrow \det((I - \lambda^{-1}T)T^{-1}) = \\
 & \Rightarrow \det(I - \lambda^{-1}T) \underbrace{\det(T^{-1})}_{\neq 0} = \\
 & = \frac{1}{\det(T)} \det\left(\frac{T - \lambda I}{-\lambda}\right) \underbrace{\neq 0}_{\neq 0} \underbrace{\det(T - \lambda I)}_{=0} \\
 & \underline{= 0}
 \end{aligned}$$

Ec. caract.

$$\begin{aligned}\lambda^{-3} - I_1(T^{-1})\lambda^{-2} + I_2(T^{-1})\lambda^{-1} - I_3(T^{-1}) \\ = 0\end{aligned}$$

Cayley-Hamilton

$$\underline{T}^3 - I_1(\underline{T})\underline{T}^2 + I_2(\underline{T})\underline{T} - I_3(\underline{T})\underline{I} = 0$$

$$\times \underline{T}^{-1} : \underline{T}^2 - I_1 \underline{T} + I_2 \underline{I} - I_3 \underline{T}^{-1} = 0$$

$$\underline{T}^{-1} = \frac{1}{I_3} (\underline{T}^2 - I_1 \underline{T} + I_2 \underline{I})$$

$$I_1(\underline{T}^{-1}) = \frac{1}{I_3} \text{tr}(\underline{T}^2) - \frac{I_1}{I_3} \underbrace{\text{tr}(\underline{I})}_{=1} + \frac{I_2}{I_3} \underbrace{\text{tr}(\underline{I})}_{=3}$$

$$I_1(T^{-1}) = \frac{1}{I_3} \text{tr}(T^2) - \frac{I_1^2}{I_3} + 3 \frac{I_2}{I_3} = \frac{I_2}{I_3}$$

$\rightarrow -2 \frac{I_2}{I_3}$
 $\frac{I_2}{I_3} = \frac{I_2}{I_3}$

$$I_2 = \frac{1}{2} \left\{ \underbrace{(\text{tr}(T))^2}_{I_1^2} - \text{tr}(T^2) \right\}$$

$$T^{-1} = \frac{1}{I_3} (T^2 - I_1 T + I_2 I) \quad (1)$$

$$I_2 (T^{-1}) = \frac{1}{2} \left[\underbrace{\text{tr}^2(T^{-1})}_{[I_1(T^{-1})]^2} - \text{tr}(T^{-2}) \right]$$

$$(1) \times T^{-1} \Rightarrow T^{-2} = \frac{1}{I_3} (T - I_1 I + I_2 T^{-1})$$

$$\text{tr}(T^{-2}) = \frac{1}{I_3} \left(I_1 - 3 \frac{I_1^2}{I_3} + \frac{I_2^2}{I_3} \right) = -2 \frac{I_1}{I_3} + \left(\frac{I_2}{I_3} \right)^2$$

$S_i S T = T S \iff S \text{ y } T \text{ coaxiales}$

$$S = \sum_i s_i U^{(i)} \otimes U^{(i)}$$

$$U^{(i)} = V^{(i)}$$

$$T = \sum_i t_i V^{(i)} \otimes V^{(i)}$$

$$S V^{(i)} = s_i V^{(i)} \rightarrow \text{No summa en } i$$

$$\left. \begin{array}{l} T(S V^{(i)}) = s_i \underbrace{T V^{(i)}} = s_i t_i V^{(i)} \\ S(T V^{(i)}) = t_i s_i V^{(i)} \end{array} \right\} \Rightarrow TS = ST$$

$$T = \begin{bmatrix} 2,5 & -0,5 & 0 \\ -0,5 & 2,5 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

$$\lambda_1 = 2, \quad v^{(1)} = \begin{bmatrix} -\sqrt{2}/2 \\ -\sqrt{2}/2 \\ 0 \end{bmatrix}$$

$$\lambda_2 = 3, \quad v^{(2)} = \begin{bmatrix} -\sqrt{2}/2 \\ \sqrt{2}/2 \\ 0 \end{bmatrix}$$

$$\lambda_3 = 4 \Rightarrow v^{(3)} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$Q_{ij} = e'_i \cdot e_j$$

$$e'_j = v^{(j)}$$

$$\overline{T}_{ij} = Q_{ik} Q_{je} \overline{T}_{ke}$$

$$Q_{ij} = e'_i \cdot e_j = [V^{(i)}]_{j_i}$$

$$\Rightarrow Q = \begin{bmatrix} V^{(1)T} \\ \vdots \\ V^{(2)T} \\ \vdots \\ V^{(n)T} \end{bmatrix}$$

$$Q^T = \begin{bmatrix} V^{(1)} & | & V^{(2)} & | & V^{(n)} \\ \vdots & & \vdots & & \vdots \end{bmatrix}$$

$$T'_{ij} = Q_{ik} Q_{je} T_{ke} = Q_{ik} T_{ke} Q_{ej} = [Q^T Q^T]_{ij}$$

$$I_2(T^{-1}) = \frac{1}{2} \left[\left(\frac{I_2}{I_3} \right)^2 - \left(\frac{I_2}{I_3} \right)^2 + 2 \frac{I_1}{I_3} \right] = \frac{I_1}{I_3}$$

$$I_3(T^{-1}) = \det(T^{-1}) = \frac{1}{\det(T)} = \frac{1}{I_3}$$